

## Matrix LED Drive Control with Keyboard Scan

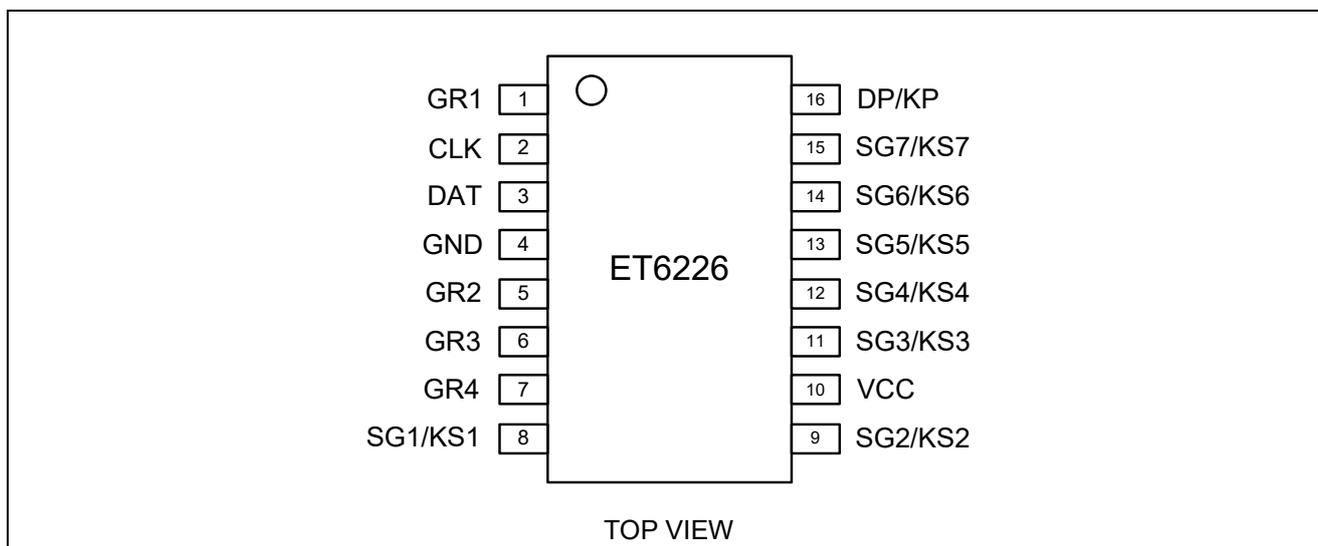
### General Description

ET6226 is a specific LED drive control circuit with a keyboard scanning interface circuit. Internal integrated MCU digital interface input and output, data latches, LED drives, keyboard scanning, brightness adjustment and so on. The chip performance is stable, reliable quality, anti-interference ability, can be adapted to work in 24 hours of continuous long-term applications.

### Features

- Display matrix mode: 8×4 or 7×4
- Segment drive current is not less than 25mA, bit drive current is not less than 150mA
- Provide eight brightness control
- Keyboard scanning: 7×4bit
- High-speed two-wire serial interface
- Built-in clock oscillator circuit
- Built-in power-on reset circuit
- Supports 3.0V~5.5V supply voltage

### Pin Configuration



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### Pin Description

Symbol	Pin name	Description
SG1/KS1~ SG7/KS7	Segment drive output /keyboard scanning input	LED segment high side drive output, Also used as key scan input, active high, internal pull-down
GR1~GR4	Bit/keyboard scanning output	LED low side drive output,Also used as key scan output
DP/KP	Segment/Bit output	LED segment output, also output for keyboard symbol
CLK	Clock input	Clock input, internal pull-up resistor
DAT	Data output/input	Data input and output, built-in drain mode pull-on
VCC	Supply voltage	3V~5.5V Power Supply pin
GND	Ground	Ground pin

### Functional Description

#### Two-wire Bus Interface

The ET6226 and MCU can transmit signal by DAT and CLK serial signal. DAT and CLK constitute two-wire interface.

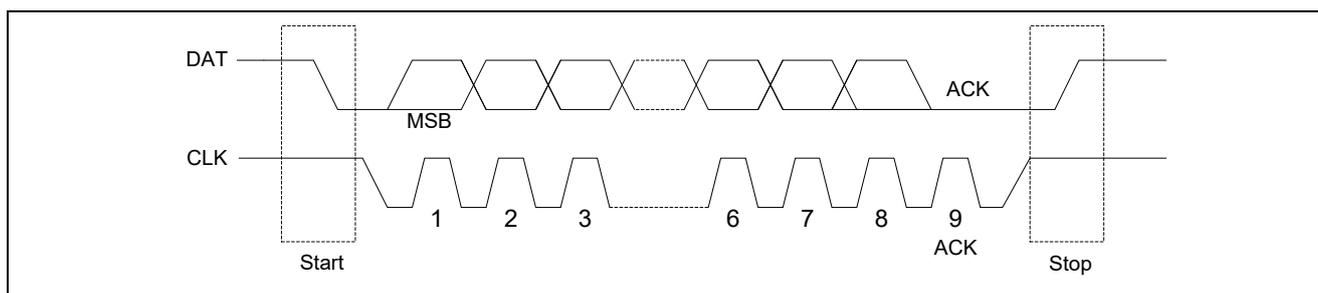
#### Data signal

When CLK signal is high, DAT signal must be stable. The high or low state of the DAT signal can only change when the CLK signal is low.

#### Start and stop condition

When the CLK signal is high, DAT signal from high to low transition, This situation indicates serial signal transmission start.

When the CLK signal is high, DAT signal from low to high transition, This situation indicates serial signal transmission stop. As show blow:



#### Command signal format

DAT format of the command signal has 8 bit, after each command signal the need for a confirmation signal, and the maximum signal bit “MSB” headed sent.

#### Format of acknowledge signal

DAT bus is set to high impedance state by the MCU during the ninth clock cycle, if ET6226 confirm this signal, then the DAT will be pulled low by the ET6226, the DAT bus to maintain a stable low state.

The ET6226 will produce a confirmation signal after received each command signal, or in the ninth clock will remain high level.

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### No acknowledge signal transmission

If you want to omit the ET6226 to acknowledge signal detection, you can use a simple transmission. The way for ET6226 in receiving a command signal, wait for a clock pulse, not to acknowledge. If you use this method will likely result in transmission errors, and will reduce the anti-jamming capability.

### Control Program Format

ET6226 control program format as show below, under the command of SYSON show:

	<b>B7</b>	<b>B6</b>	<b>B5</b>	<b>B4</b>	<b>B3</b>	<b>B2</b>	<b>B1</b>	<b>B0</b>		<b>B7</b>	<b>B6</b>	<b>B5</b>	<b>B4</b>	<b>B3</b>	<b>B2</b>	<b>B1</b>	<b>B0</b>		
Start	0	1	0	0	1	0	0	0	Ack	0	0	0	0	0	0	0	1	Ack	Stop

### Status Control Command Format

High 8 bits data:48H

<b>B7</b>	<b>B6</b>	<b>B5</b>	<b>B4</b>	<b>B3</b>	<b>B2</b>	<b>B1</b>	<b>B0</b>
0	1	0	0	1	0	0	0

Low 8 bits data is follow:

<b>B7</b>	<b>B6</b>	<b>B5</b>	<b>B4</b>	<b>B3</b>	<b>B2</b>	<b>B1</b>	<b>B0</b>	<b>Function</b>	<b>Description</b>
0								Don't care	Please set to 0
	0	0	0					8 steps brightness adjust	8 step (highest brightness)
	0	0	1						1 step (lowest brightness)
	...	...	...						...
	1	1	1						7step
				1				Mode selection	7 segment
				0					8 segment (DP/KP) as SG output
					1			Sleep command	Sleep mode
					0				Operation mode
						0		Don't care	Please set to 0
							1	Display switch	Display ON
							0		Display OFF

For example: “48H,X1H” is 8 segment mode, “X” is brightness step; “48H,X9H” is 7 segment mode; “48H,04H” is sleep mode.

**Note:** D0 and D2 cannot be “1” at the same time.

**Note:** when the circuit operate at 7 segment mode or 8 segment mode, DP/KP ports working condition is different, and need the peripheral circuit is also different.

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**Display Data Command**

High 8-bit	Display Data (Low 8-bit)								
	DP/KP	SG7/KS7	SG6/KS6	SG5/KS5	SG4/KS4	SG3/KS3	SG2/KS2	SG1/KS1	
68H	B7	B6	B5	B4	B3	B2	B1	B0	<b>GR1</b>
6AH	B7	B6	B5	B4	B3	B2	B1	B0	<b>GR2</b>
6CH	B7	B6	B5	B4	B3	B2	B1	B0	<b>GR3</b>
6EH	B7	B6	B5	B4	B3	B2	B1	B0	<b>GR4</b>

**Key Code Command**

High 8-bit	Return Key Codes (Low 8-bit)							
4FH	B7	B6	B5	B4	B3	B2	B1	B0

	GR1	GR2	GR3	GR4
SG1/KS1	44H	45H	46H	47H
SG2/KS2	4CH	4DH	4EH	4FH
SG3/KS3	54H	55H	56H	57H
SG4/KS4	5CH	5DH	5EH	5FH
SG5/KS5	64H	65H	66H	67H
SG6/KS6	6CH	6DH	6EH	6FH
SG7/KS7	74H	75H	76H	77H

**Matrix LED Drive Control with Keyboard Scan**
**Absolute Maximum Ratings (T<sub>A</sub> = 25°C)**

Symbol	Parameter	Range	Unit
V <sub>CC</sub>	Power supply	-0.5 ~ +6.5	V
V <sub>I</sub>	I/O port Input voltage	-0.5 ~ V <sub>CC</sub> + 0.5	V
I <sub>CC</sub>	Max power input current	150	mA
T <sub>OPT</sub>	Operating ambient temperature	-40 ~ +85	°C
T <sub>STG</sub>	Storage temperature	-55 ~ +125	°C
T <sub>J</sub>	Operating junction temperature	-40 ~ +150	°C

**Electrical Characteristics**

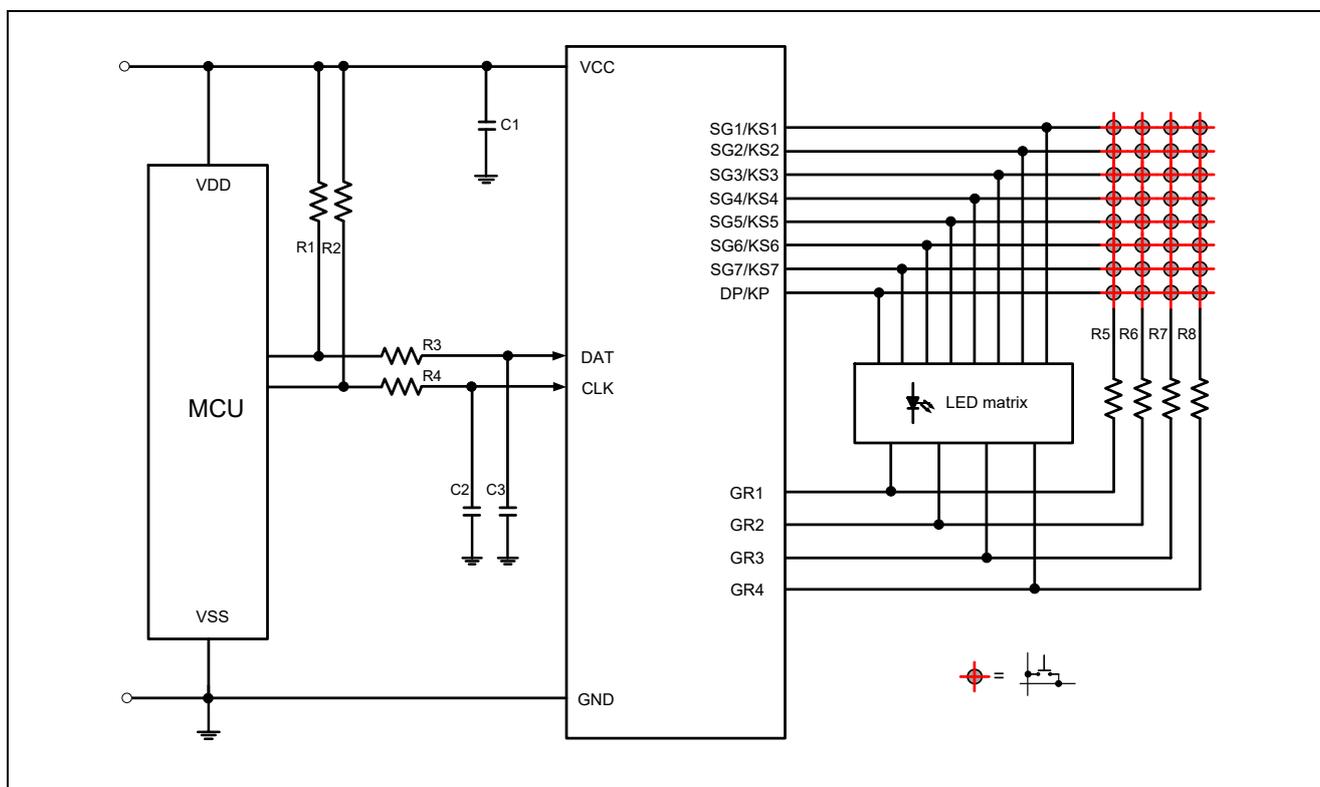
 Test Condition: T<sub>A</sub> = 25°C, V<sub>CC</sub> = 5V

Symbol	Parameter	Min	Typ	Max	Unit
V <sub>CC</sub>	Supply voltage	3	5	5.5	V
I <sub>Q</sub>	Quiescent current (CLK、DAT、KP is high)		0.3	0.6	mA
I <sub>Q_OFF</sub>	Sleep current (CLK、DAT、KP is high)		0.05	0.1	mA
V <sub>IL</sub>	CLK and DAT pin low level input voltage	-0.5		0.2V <sub>CC</sub>	V
V <sub>IH</sub>	CLK and DAT pin high level input voltage	0.7V <sub>CC</sub>		V <sub>CC</sub> +0.5	V
V <sub>ILki</sub>	KS pin low level input voltage	-0.5		0.5	V
V <sub>IHki</sub>	KS pin high level input voltage	1.8		V <sub>CC</sub> +0.5	V
V <sub>OLDig</sub>	GR pin low level input voltage (-200mA)			1.2	V
V <sub>OLDig</sub>	GR pin low level input voltage (-100mA)			0.8	V
V <sub>OHDig</sub>	GR pin high level input voltage (5mA)	4.5			V
V <sub>OLki</sub>	KS pin low level input voltage (-20mA)			0.5	V
V <sub>OHki</sub>	KS pin high level input voltage (20mA)	4.5			V
I <sub>DN1</sub>	KS pin pull-down current	-30	-50	-90	μA
I <sub>UP1</sub>	CLK pin input pull-up current	100	200	300	μA
I <sub>UP2</sub>	DAT pin input pull-up current	150	300	400	μA
I <sub>UP3</sub>	KP pin output pull-up current	500	2000	5000	μA
V <sub>RESET</sub>	The default power-on reset threshold voltage	2.3	2.6	2.9	V



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Typical Application



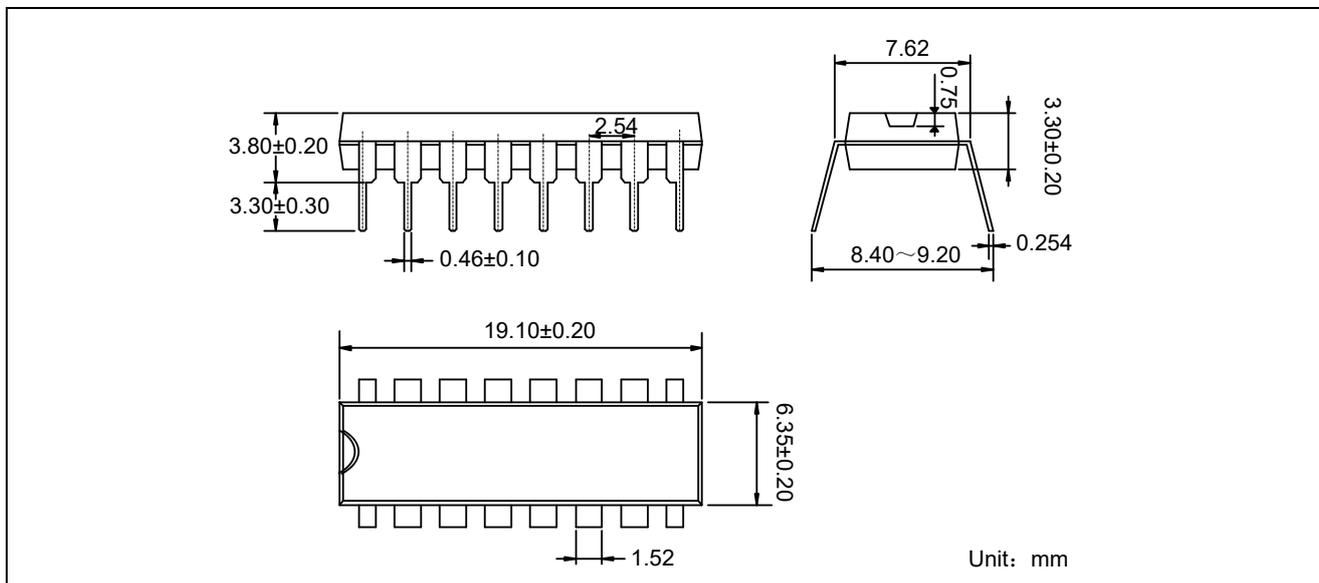
**\*Note:**

1. This application circuit is only for reference.
2. C1=1uF and should be placed as close as possible to the VCC.
3. R1,R2 = 4.7kΩ; R3,R4 = 100Ω; C2,C3 = 100pF; R5~R8 = 2kΩ.
4. The series resistance of the communication port and the capacitor for GND should be placed as close as possible to ET6226, and the resistance value and capacitance value should be adjusted according to the actual anti-interference requirements and verification results.

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Package Information

DIP16



SOP16

